

Low Rank Bilinear Algorithms for Symmetric Tensor Contractions

Edgar Solomonik

ETH Zurich

SIAM PP, Paris, France

April 14, 2016

Tensor contractions

For some $s, t, v \geq 0$, a tensor contraction of tensors A and B is

$$C_{\vec{ij}} = \sum_{\vec{k}} A_{\vec{ik}} \cdot B_{\vec{kj}}, \quad \text{alternatively written,} \quad C_{\vec{j}}^{\vec{i}} = \sum_{\vec{k}} A_{\vec{k}}^{\vec{i}} \cdot B_{\vec{j}}^{\vec{k}},$$

where $\vec{i} = \{i_1, \dots, i_s\}$, $\vec{j} = \{j_1, \dots, j_t\}$, and $\vec{k} = \{k_1, \dots, k_v\}$.

Matrix/vector examples:

- $(s, t, v) = (0, 0, 1)$ vector inner product
- $(s, t, v) = (1, 0, 1)$ matrix-vector multiplication
- $(s, t, v) = (1, 1, 0)$ vector outer product
- $(s, t, v) = (1, 1, 1)$ matrix-matrix multiplication
- $(s, t, v) = (s, 1, 1)$ tensor-times-matrix

Applications of higher-order tensor contractions

Some applications of contractions of tensors of order at least three:

- tensor factorization algorithms, e.g. alternating least squares
- deep learning convolutional neural networks
- higher-order analysis of probabilistic correlation
- post-Hartree-Fock electronic structure, e.g. coupled cluster
- density matrix renormalization group (DMRG)

Contractions in Coupled Cluster (CCSD method)

$$W_{ei}^{mn} = V_{ei}^{mn} + \sum_f V_{ef}^{mn} t_i^f,$$

$$X_{ij}^{mn} = V_{ij}^{mn} + P_j^i \sum_e V_{ie}^{mn} t_j^e + \frac{1}{2} \sum_{ef} V_{ef}^{mn} \tau_{ij}^{ef},$$

$$U_{ie}^{am} = V_{ie}^{am} - \sum_n W_{ei}^{mn} t_n^a + \sum_f V_{ef}^{ma} t_i^f + \frac{1}{2} \sum_{nf} V_{ef}^{mn} \tau_{in}^{af},$$

$$Q_{ij}^{am} = V_{ij}^{am} + P_j^i \sum_e V_{ie}^{am} t_j^e + \frac{1}{2} \sum_{ef} V_{ef}^{am} \tau_{ij}^{ef},$$

$$\begin{aligned} z_i^a = & f_i^a - \sum_m F_i^m t_m^a + \sum_e f_e^a t_i^e + \sum_{em} V_{ei}^{ma} t_m^e + \sum_{em} V_{im}^{ae} F_e^m + \frac{1}{2} \sum_{efm} V_{ef}^{am} \tau_{im}^{ef} \\ & - \frac{1}{2} \sum_{emn} W_{ei}^{mn} \tau_{mn}^{ea}, \end{aligned}$$

$$\begin{aligned} Z_{ij}^{ab} = & V_{ij}^{ab} + P_j^i \sum_e V_{ie}^{ab} t_j^e + P_b^a P_j^i \sum_{me} U_{ie}^{am} \tau_{mj}^{eb} - P_b^a \sum_m Q_{ij}^{am} t_m^b \\ & + P_b^a \sum_e F_e^a \tau_{ij}^{eb} - P_j^i \sum_m F_i^m \tau_{mj}^{ab} + \frac{1}{2} \sum_{ef} V_{ef}^{ab} \tau_{ij}^{ef} + \frac{1}{2} \sum_{mn} X_{ij}^{mn} \tau_{mn}^{ab}, \end{aligned}$$

where $P_y^x f(x, y) := f(x, y) - f(y, x)$

Exploiting symmetry in tensor contractions

Tensor symmetry (e.g. $A_{ij} = A_{ji}$) reduces memory and cost

- for order d tensor, $d!$ less memory
- dot product $\sum_{i,j} A_{ij} B_{ij} = 2 \sum_{i < j} A_{ij} B_{ij} + \sum_i A_{ii} B_{ii}$
- matrix-vector multiplication ($A_{ij} = A_{ji}$)

$$c_i = \sum_j A_{ij} b_j = \sum_j A_{ij} (b_i + b_j) - \left(\sum_j A_{ij} \right) b_i$$

- $A_{ij} b_j \neq A_{ji} b_i$ but $A_{ij} (b_i + b_j) = A_{ji} (b_j + b_i) \rightarrow (1/2)n^2$ multiplies
- partially-symmetric case: $T_{ij}^{ab} = -T_{ji}^{ab}$

$$\begin{aligned} W_{ic}^{ak} &= \sum_j \sum_b T_{ij}^{ab} V_{bc}^{jk} \\ &= \sum_j \left(\sum_b T_{ij}^{ab} (V_{bc}^{ik} + V_{bc}^{jk}) \right) - \sum_b \left(\sum_j T_{ij}^{ab} \right) V_{bc}^{ik} \end{aligned}$$

- $Z_{ijc}^{ak} = \sum_b T_{ij}^{ab} (V_{bc}^{ik} + V_{bc}^{jk}) = -Z_{jic}^{ak} \rightarrow$ **2x fewer operations**

Symmetry preserving algorithms

By exploiting symmetry, reduce multiplies (but increase adds)

- rank-2 vector outer product

$$C_{ij} = a_i b_j + a_j b_i = (a_i + a_j)(b_i + b_j) - a_i b_i - a_j b_j$$

- squaring a symmetric matrix A (or $AB + BA$)

$$C_{ij} = \sum_k A_{ik} A_{kj} = \sum_k (A_{ik} + A_{kj} + A_{ij})^2 - \dots$$

- fully symmetric contraction of order $s + v$ and $v + t$ tensors

$$\frac{(s + t + v)!}{s!t!v!} \quad \text{fewer multiplies}$$

e.g. cases above are

- $(s, t, v) = (1, 1, 0) \rightarrow$ reduction by 2X
- $(s, t, v) = (1, 1, 1) \rightarrow$ reduction by 6X

Applications of symmetry preserving algorithms

Extensions and applications:

- numerically stable by forward error bounds and experiments
- for Hermitian tensors, multiplies cost 3X more than adds
 - Hermitian matrix multiplication and tridiagonal reduction (BLAS and LAPACK routines) with 25% fewer operations
- cost reductions in partially-symmetric coupled cluster contractions: 2X-9X for select contractions, 1.3X, 2.1X for CCSD, CCSDT
- $(2/3)n^3$ multiplies for squaring a *nonsymmetric* matrix

$$X_{SY} := \frac{1}{2}(X + X^T), \quad X_{AS} := \frac{1}{2}(X - X^T),$$

$$C = AB + (A^T B^T)^T = AB + BA$$

$$= (A_{SY} B_{SY})_{SY} + (A_{SY} B_{AS})_{AS} + (A_{AS} B_{SY})_{AS} + (A_{AS} B_{AS})_{SY}$$

four invocations of $(s, t, v) = (1, 1, 1)$, squaring when $A = B$

Symmetry preserving blocking (sketch)

Multiplication of a symmetric matrix A and a nonsymmetric matrix B :

- classical approach, two choices:
 - 1 treat A as nonsymmetric (unpack if stored as symmetric)
 - 2 multiply by lower-triangle of A then by its transpose
- proposed new approach
 - fold $n \times n$ matrix A into $\sqrt{p} \times \frac{n}{\sqrt{p}} \times \sqrt{p} \times \frac{n}{\sqrt{p}}$ tensor T
 - note that $T_{kl}^{ij} = T_{lk}^{ij}$, define partially-symmetric $Y_{kl}^{ij} = T_{kl}^{ij} + T_{lk}^{ij}$ and partially-antisymmetric $S_{kl}^{ij} = T_{kl}^{ij} - T_{lk}^{ij}$
 - use symmetry preserving alg. over indices of dims $\sqrt{p} \times \sqrt{p}$, results in p subproblems with symmetric matrices with dims $\frac{n}{\sqrt{p}} \times \frac{n}{\sqrt{p}}$
- food for thought: keep folding/symmetrizing to $2 \times \dots \times 2$ tensors
→ Hankel matrices (modulo sign interchanges)

Bilinear algorithms as tensor factorizations

A bilinear algorithm corresponds to a CP tensor decomposition

$$\begin{aligned}c_i &= \sum_{r=1}^R F_{ir}^{(C)} \left(\sum_j F_{jr}^{(A)} a_j \right) \left(\sum_k F_{kr}^{(B)} b_k \right) \\ &= \sum_j \sum_k \left(\sum_{r=1}^R F_{ir}^{(C)} F_{jr}^{(A)} F_{kr}^{(B)} \right) a_j b_k \\ &= \sum_j \sum_k T_{ijk} a_j b_k \quad \text{where} \quad T_{ijk} = \sum_{r=1}^R F_{ir}^{(C)} F_{jr}^{(A)} F_{kr}^{(B)}\end{aligned}$$

For multiplication of $n \times n$ matrices,

- T is $n^2 \times n^2 \times n^2$
- classical algorithm has rank $R = n^3$
- Strassen's algorithm has rank $R \approx n^{\log_2(7)}$

Bilinear algorithms as tensor factorizations

A bilinear algorithm corresponds to a CP tensor decomposition

$$\begin{aligned}c_i &= \sum_{r=1}^R F_{ir}^{(C)} \left(\sum_j F_{jr}^{(A)} a_j \right) \left(\sum_k F_{kr}^{(B)} b_k \right) \\ &= \sum_j \sum_k \left(\sum_{r=1}^R F_{ir}^{(C)} F_{jr}^{(A)} F_{kr}^{(B)} \right) a_j b_k \\ &= \sum_j \sum_k T_{ijk} a_j b_k \quad \text{where} \quad T_{ijk} = \sum_{r=1}^R F_{ir}^{(C)} F_{jr}^{(A)} F_{kr}^{(B)}\end{aligned}$$

For symmetric tensor contractions (not counting diagonals)

- T is $\binom{n}{s+t} \times \binom{n}{s+v} \times \binom{n}{v+t}$
- classical algorithm has rank $R = \binom{n}{s} \binom{n}{t} \binom{n}{v}$
- symmetry preserving $\rightarrow R \approx \binom{n}{s+t+v}$, that is $\frac{(s+t+v)!}{s!t!v!}$ less

Expansion in bilinear algorithms

Given $\Lambda = (F^{(A)}, F^{(B)}, F^{(C)})$, $\Lambda_{\text{sub}} \subseteq \Lambda$ if \exists projection matrix P , so

$$\Lambda_{\text{sub}} = (F^{(A)}P, F^{(B)}P, F^{(C)}P),$$

the projection matrix extracts $\#_{\text{cols}}(P)$ columns of each matrix.

A bilinear algorithm Λ has expansion bound $\mathcal{E}_{\Lambda} : \mathbb{N}^3 \rightarrow \mathbb{N}$, if for all

$$\Lambda_{\text{sub}} := (F_{\text{sub}}^{(A)}, F_{\text{sub}}^{(B)}, F_{\text{sub}}^{(C)}) \subseteq \Lambda$$

we have

$$\text{rank}(\Lambda_{\text{sub}}) \leq \mathcal{E}_{\Lambda} \left(\text{rank}(F_{\text{sub}}^{(A)}), \text{rank}(F_{\text{sub}}^{(B)}), \text{rank}(F_{\text{sub}}^{(C)}) \right)$$

For matrix mult., Loomis-Whitney inequality $\rightarrow \mathcal{E}_{\text{MM}}(x, y, z) = \sqrt{xyz}$

For sym. pres. $\mathcal{E}_{\text{SP}}^{(s,t,v)}(x, y, z) = O\left(\min\left(x^{\frac{s+t+v}{s+v}}, y^{\frac{s+t+v}{t+v}}, z^{\frac{s+t+v}{s+t}}\right)\right)$

Communication in symmetry preserving algorithms

Communication lower bounds based on bilinear algorithm expansion

- horizontal comm. – max data sent or received
- vertical comm. – max data moved between memory and cache

For contraction of order $s + v$ tensor with order $v + t$ tensor

- matrix-vector-like algorithms ($\min(s, t, v) = 0$)
 - vertical communication dominated by largest tensor
 - horizontal communication asymptotically greater if only unique elements are stored and $s \neq t \neq v$
- matrix-matrix-like algorithms ($\min(s, t, v) > 0$)
 - vertical and horizontal communication costs asymptotically greater for symmetry preserving algorithm when $s \neq t \neq v$

Conclusion

Summary:

- symmetry preserving algorithms reduce cost of contractions
- they have been tested using Cyclops Tensor Framework
<https://github.com/solomonik/ctf>
- rank structure of bilinear algorithms yields communication bounds

Future work:

- communication lower bounds for partially-symmetric cases
- high performance implementation

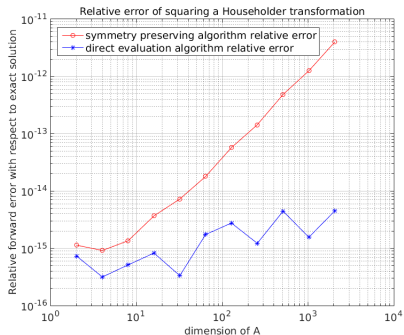
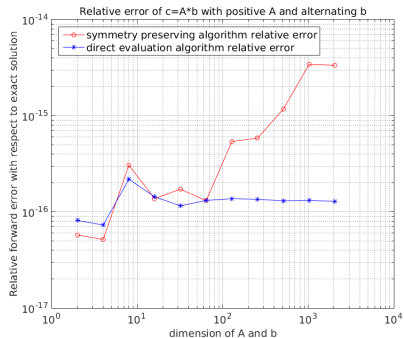
Related work: *J. Noga and P. Valiron, Improved algorithm for triple-excitation contributions within the coupled cluster approach, Molecular Physics, 103 (2005).*

References (for more, email solomonik@inf.ethz.ch):

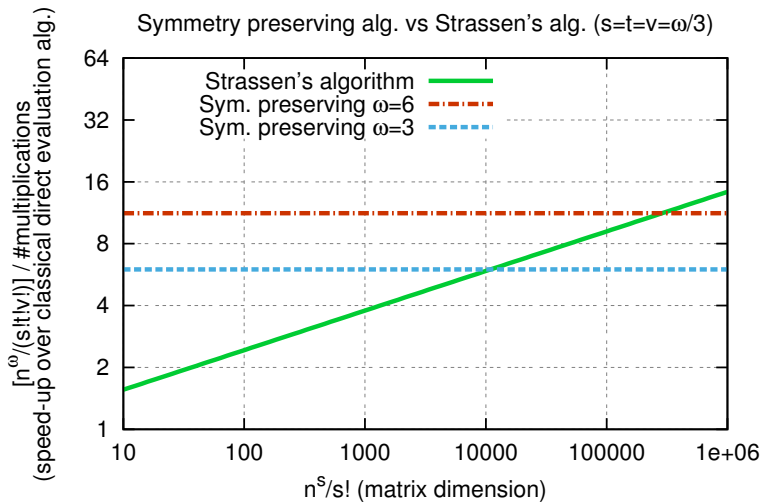
- *E.S. and J. Demmel; Contracting symmetric tensors using fewer multiplications; ETH Zurich, 2015*
- *E.S., J. Demmel, and T. Hoefler; Communication lower bounds for tensor contraction algorithms; ETH Zurich, 2015*

Backup slides

Stability of symmetry preserving algorithms



Symmetry preserving algorithm vs Strassen's algorithm



A library for tensor computations

Cyclops Tensor Framework

- implicit for loops based on index notation (Einstein summation)
- matrix sums, multiplication, Hadamard product (tensor contractions)
- distributed symmetric-packed/sparse storage via cyclic layout

Jacobi iteration (solves $Ax = b$ iteratively) example code snippet

```
Vector<> Jacobi(Matrix<> A, Vector<> b, int n){
    ... // split A = R + diag(1./d)
    do {
        x["i"] = d["i"]*(b["i"]-R["ij"]*x["j"]);
        r["i"] = b["i"]-A["ij"]*x["j"]; // compute residual
    } while (r.norm2() > 1.E-6); // check for convergence
    return x;
}
```

Coupled cluster using CTF

Extracted from Aquarius (Devin Matthews' code,
<https://github.com/devinamatthews/aquarius>)

```
FMI["mi"]      += 0.5*WMNEF["mnef"]*T2["efin"];
WMNIJ["mnij"] += 0.5*WMNEF["mnef"]*T2["efij"];
FAE["ae"]      -= 0.5*WMNEF["mnef"]*T2["afmn"];
WAMEI["amei"]  -= 0.5*WMNEF["mnef"]*T2["afin"];

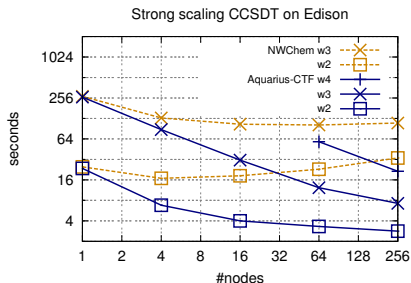
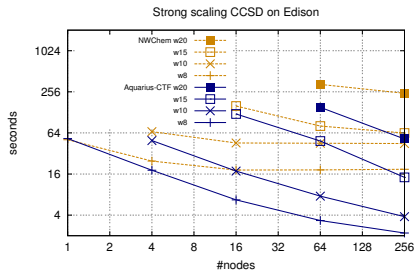
Z2["abij"]    = WMNEF["ijab"];
Z2["abij"]    += FAE["af"]*T2["fbij"];
Z2["abij"]    -= FMI["ni"]*T2["abnj"];
Z2["abij"]    += 0.5*WABEF["abef"]*T2["efij"];
Z2["abij"]    += 0.5*WMNIJ["mnij"]*T2["abmn"];
Z2["abij"]    -= WAMEI["amei"]*T2["ebmj"];
```

CTF is used within **Aquarius**, **QChem**, **VASP**, and **Psi4**

Comparison with NWChem

NWChem is the most commonly-used distributed-memory quantum chemistry method suite

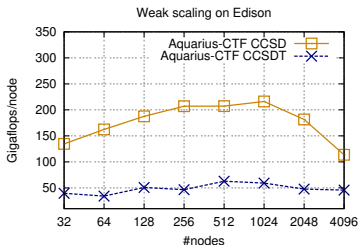
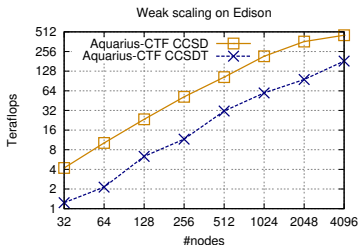
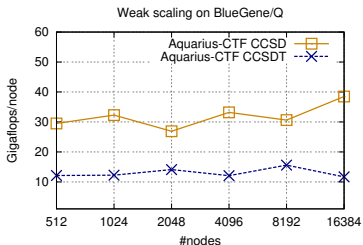
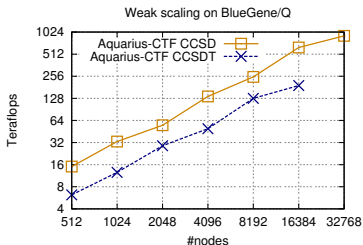
- provides Coupled Cluster methods: CCSD and CCSDT
- derives equations via Tensor Contraction Engine (TCE)
- generates contractions as blocked loops leveraging Global Arrays



Coupled cluster on IBM BlueGene/Q and Cray XC30

CCSD up to 55 (50) water molecules with cc-pVDZ

CCSDT up to 10 water molecules with cc-pVDZ^a



^aS., Matthews, Hammond, Demmel, JPDC, 2014

Coupled cluster methods

Coupled cluster provides a systematically improvable approximation to the manybody time-independent Schrödinger equation $H|\Psi\rangle = E|\Psi\rangle$

- the Hamiltonian has one- and two- electron components

$$H = F + V$$

- Hartree-Fock (SCF) computes mean-field Hamiltonian: F , V
- Coupled-cluster methods (CCSD, CCSDT, CCSDTQ) consider transitions of (doubles, triples, and quadruples) of electrons to unoccupied orbitals, encoded by tensor operator,

$$T = T_1 + T_2 + T_3 + T_4$$

- they use an exponential ansatz for the wavefunction, $\Psi = e^T \phi$ where ϕ is a Slater determinant
- expanding $0 = \langle \phi' | H | \Psi \rangle$ yields nonlinear equations for $\{T_i\}$ in F , V

$$0 = V_{ij}^{ab} + P(a, b) \sum_e T_{ij}^{ae} F_e^b - \frac{1}{2} P(i, j) \sum_{mnef} T_{im}^{ab} V_{ef}^{mn} T_{jn}^{ef} + \dots$$

where P is an antisymmetrization operator

Vertical communication in bilinear algorithms

Any schedule on a sequential machine with a cache of size H for $\Lambda = (F^{(A)}, F^{(B)}, F^{(C)})$ with expansion bound \mathcal{E}_Λ has vertical communication cost,

$$Q_\Lambda \geq \max \left[\frac{2 \operatorname{rank}(\Lambda) H}{\mathcal{E}_\Lambda^{\max}(H)}, \# \text{rows}(F^{(A)}) + \# \text{rows}(F^{(B)}) + \# \text{rows}(F^{(C)}) \right]$$

where $\mathcal{E}_\Lambda^{\max}(H) := \max_{c^{(A)}, c^{(B)}, c^{(C)} \in \mathbb{N}, c^{(A)} + c^{(B)} + c^{(C)} = 3H} \mathcal{E}_\Lambda(c^{(A)}, c^{(B)}, c^{(C)})$

Vertical communication in matrix multiplication

For the classical (non-Strassen-like) matrix multiplication algorithm of m -by- k matrix A with k -by- n matrix B into m -by- n matrix C ,

$$\mathcal{E}_{\text{MM}}(c^{(A)}, c^{(B)}, c^{(C)}) = (c^{(A)}c^{(B)}c^{(C)})^{1/2}$$

further, we have

$$\mathcal{E}_{\text{MM}}^{\max}(H) = \max_{c^{(A)}, c^{(B)}, c^{(C)} \in \mathbb{N}, c^{(A)}+c^{(B)}+c^{(C)} \leq 3H} (c^{(A)}c^{(B)}c^{(C)})^{1/2} = H^{3/2}$$

so we obtain the expected bound,

$$\begin{aligned} Q_{\text{MM}} &\geq \max \left[\frac{2 \text{rank}(\text{MM})H}{\mathcal{E}_{\text{MM}}^{\max}(H)}, \# \text{rows}(F^{(A)}) + \# \text{rows}(F^{(B)}) + \# \text{rows}(F^{(C)}) \right] \\ &= \max \left[\frac{2mnk}{\sqrt{H}}, mk + kn + mn \right] \end{aligned}$$

Horizontal communication in bilinear algorithms

Any load balanced schedule on a parallel machine with p processes of $\Lambda = (F^{(A)}, F^{(B)}, F^{(C)})$ with expansion bound \mathcal{E}_Λ has horizontal communication cost,

$$W_\Lambda \geq c^{(A)} + c^{(B)} + c^{(C)}$$

for some (communicated amounts) $c^{(A)}, c^{(B)}, c^{(C)} \in \mathbb{N}$ such that,

$$\begin{aligned} \text{rank}(\Lambda)/p &\leq \mathcal{E}_\Lambda(c^{(A)} + \#\text{rows}(F^{(A)})/p, \\ &\quad c^{(B)} + \#\text{rows}(F^{(B)})/p, \\ &\quad c^{(C)} + \#\text{rows}(F^{(C)})/p) \end{aligned}$$

Horizontal communication in matrix multiplication

For the classical (non-Strassen-like) matrix multiplication algorithm of m -by- k matrix A with k -by- n matrix B into m -by- n matrix C on a parallel machine of p processors,

$$W_{\text{MM}} = \Omega (W_{\text{O}}(\min(m, n, k), \text{median}(m, n, k), \max(m, n, k), p))$$

where

$$W_{\text{O}}(x, y, z, p) = \begin{cases} \left(\frac{xyz}{p}\right)^{2/3} & : p > yz/x^2 \\ x \left(\frac{yz}{p}\right)^{1/2} & : yz/x^2 \geq p > z/y \\ xy & : z/y \geq p \end{cases}$$

Communication lower bounds for direct evaluation of symmetric contractions

An expansion bound on $\Psi^{(s,t,v)}$ is

$$\mathcal{E}_{\Psi}^{(s,t,v)}(\mathbf{c}^{(A)}, \mathbf{c}^{(B)}, \mathbf{c}^{(C)}) = q \left(\mathbf{c}^{(A)} \mathbf{c}^{(B)} \mathbf{c}^{(C)} \right)^{1/2},$$

where $q = \left[\binom{s+v}{s} \binom{v+t}{v} \binom{s+t}{s} \right]^{1/2}$.

Therefore, the same (asymptotically) horizontal and vertical communication lower bounds apply for $\Psi^{(s,t,v)}$ as for a matrix multiplication with dimensions $n^s \times n^t \times n^v$.

Communication lower bounds for direct evaluation of symmetric contractions

Another expansion bound on $\Psi^{(s,t,0)}$ (when $v = 0$) is

$$\mathcal{E}_{\Psi}^{(s,t,0)}(c^{(A)}, c^{(B)}, c^{(C)}) = \left(\binom{\omega}{s} - 1 \right) c^{(C)} + \min \left((c^{(A)})^{\omega/s}, (c^{(B)})^{\omega/t}, c^{(C)} \right)$$

There are also symmetric bounds when $s = 0$ or $t = 0$.

When exactly one of s, t, v is zero, any load balanced schedule of $\Psi^{(s,t,v)}$ on a parallel machine with p processors has horizontal communication cost,

$$W_{\Psi} = \Omega \left((n^{\omega}/p)^{\max(s,t,v)/\omega} \right)$$

This can be greater than the corresponding nonsymmetric bound,

$$W_{\Psi} = \Omega \left((n^{\omega}/p)^{1/2} \right)$$

Communication lower bounds for the symmetry preserving algorithm

An expansion bound on $\Phi^{(s,t,v)}$ is

$$\mathcal{E}_{\Phi}^{(s,t,v)}(\mathbf{c}^{(A)}, \mathbf{c}^{(B)}, \mathbf{c}^{(C)}) = \min \left(\left(\binom{\omega}{t} \mathbf{c}^{(A)} \right)^{\frac{\omega}{s+v}}, \right. \\ \left. \left(\binom{\omega}{s} \mathbf{c}^{(B)} \right)^{\frac{\omega}{v+t}}, \right. \\ \left. \left(\binom{\omega}{v} \mathbf{c}^{(C)} \right)^{\frac{\omega}{s+t}} \right)$$

This yields communication bounds with $\kappa := \max(s + v, v + t, s + t)$,

$$Q_{\Phi} = \Omega \left(\frac{n^{\omega} H}{H^{\omega/\kappa}} + n^{\kappa} \right) \quad W_{\Phi} = \begin{cases} \Omega \left((n^{\omega}/p)^{\kappa/\omega} \right) & : s, t, v > 0 \\ \Omega \left((n^{\omega}/p)^{\max(s,t,v)/\omega} \right) & : \kappa = \omega \end{cases}$$

Nesting of bilinear algorithms

Given two bilinear algorithms:

$$\Lambda_1 = (F_1^{(A)}, F_1^{(B)}, F_1^{(C)})$$

$$\Lambda_2 = (F_2^{(A)}, F_2^{(B)}, F_2^{(C)})$$

We can nest them by computing their tensor product

$$\Lambda_1 \otimes \Lambda_2 := (F_1^{(A)} \otimes F_2^{(A)}, F_1^{(B)} \otimes F_2^{(B)}, F_1^{(C)} \otimes F_2^{(C)})$$

$$\text{rank}(\Lambda_1 \otimes \Lambda_2) = \text{rank}(\Lambda_1) \cdot \text{rank}(\Lambda_2)$$

Communication lower bounds for nested algorithms

Conjecture: if bilinear algorithms λ_1 and λ_2 have expansion bounds \mathcal{E}_1 and \mathcal{E}_2 , then $\lambda_1 \otimes \lambda_2$ has expansion bound, $\mathcal{E}_{12}(c^{(A)}, c^{(B)}, c^{(C)})$

$$= \max_{\substack{c_1^{(A)}, c_1^{(B)}, c_1^{(C)}, c_2^{(A)}, c_2^{(B)}, c_2^{(C)} \in \mathbb{N} \\ c_1^{(A)} c_2^{(A)} = c^{(A)}, c_1^{(B)} c_2^{(B)} = c^{(B)}, c_1^{(C)} c_2^{(C)} = c^{(C)}}} \left[\mathcal{E}_1(c_1^{(A)}, c_1^{(B)}, c_1^{(C)}) \mathcal{E}_2(c_2^{(A)}, c_2^{(B)}, c_2^{(C)}) \right]$$

Simplified conjecture: consider matrices A and B , such that for some $\alpha, \beta \in [0, 1]$ and any $k \in \mathbb{N}$

- any subset of k columns of A has rank at least k^α
- any subset of k columns of B has rank at least k^β

then any subset of $k \in \mathbb{N}$ columns of $A \otimes B$ has rank at least $k^{\min(\alpha, \beta)}$

The first conjecture would provide lower bounds for the nested algorithms we wish to use for partially-symmetric coupled-cluster contractions.